

Homework #1, Micro III, Spring 2007  
Maxwell B. Stinchcombe

All random variables are defined on a probability space  $(\Omega, \mathcal{F}, P)$ . Throughout,  $X, X', Y : \Omega \rightarrow \mathbb{R}$  are random variables having finite range, and  $P(Y = 1) = P(Y = 2) = \frac{1}{2}$ .

Time line: first,  $\omega \in \Omega$  is drawn according to  $P$ ; then the value of a signal  $X(\omega)$  or  $X'(\omega)$  is observed; then a choice  $a \in A$  is made; and finally the utility  $u(a, Y(\omega))$  is received.

Notation and definitions:

1.  $\beta_x^X := P(Y = 1 | X = x)$  is the **posterior probability**, aka **belief** that  $Y = 1$  given that  $X = x$ ;
2.  $V_{u,A}(X) := \max_{f:S \rightarrow A} E u(f(X), Y)$ ;
3. the **convex hull** of  $C \subset \mathbb{R}^k$  is written **con**( $C$ );  $A^S$  is the set of functions  $f : S \rightarrow A$ ;
4. for a (finite) set  $C$ ,  $\Delta(C) = \{p \in \mathbb{R}_+^C : \sum_{c \in C} p_c = 1\}$  is the set of probability distributions over  $C$ ;
5. the range of a function  $X : \Omega \rightarrow \mathbb{R}$  is  $\mathcal{R}(X) = \{r \in \mathbb{R} : (\exists \omega \in \Omega)[X(\omega) = r]\}$ ;
6. for  $p, q$  distribution on  $\mathbb{R}^k$ ,  $k \geq 2$ ,  $p$  is **riskier** than  $q$  if for all continuous, concave  $g : \mathbb{R}^k \rightarrow \mathbb{R}$ ,  $\int g(x) dp(x) \leq \int g(x) dq(x)$ ;
7. for distributions  $p, q$  on  $\mathbb{R}^1$ ,  $q$  is **riskier** than  $p$  if for all continuous, concave, non-decreasing  $g : \mathbb{R}^1 \rightarrow \mathbb{R}$ ,  $\int g(x) dp(x) \geq \int g(x) dq(x)$ .
8. for distributions  $p, q$  on  $\mathbb{R}^1$ ,  $q$  is a **mean preserving spread** of  $p$  if  $\int x dq(x) = \int x dp(x)$  and there is an interval  $|a, b| \subset \mathbb{R}$ , such that
  - a. for all  $E \subset (a, b]$ ,  $q(E) \leq p(E)$ ,
  - b. for all  $E \subset (b, \infty)$ ,  $q(E) \geq p(E)$ , and
  - c. for all  $E \subset (-\infty, a]$ ,  $q(E) \geq p(E)$ .
9. For  $r \in \mathbb{R}$ ,  $\delta_r$  is point mass on  $\mathbb{R}$ , that is,  $\delta_r(E) = 1_E(r)$ .
10. for distributions  $p, q$  on  $\mathbb{R}^1$ ,  $p$  **first order stochastically dominates**  $q$  if for all non-decreasing  $g : \mathbb{R} \rightarrow \mathbb{R}$ ,  $\int g(x) dp(x) \geq \int g(x) dq(x)$ .

1. Consider the problem  $(u, A)$  and the random variables  $X, X'$  given by

$a = 3$	0	40
$a = 2$	30	30
$a = 1$	50	0
	$Y = 1$	$Y = 2$

$X = 2$	0.3	0.8
$X = 1$	0.7	0.2
	$Y = 1$	$Y = 2$

$X' = 2$	0.1	0.7
$X' = 1$	0.9	0.3
	$Y = 1$	$Y = 2$

where, e.g.  $50 = u(a = 1, Y = 1)$  and  $0.3 = P(X = 2|Y = 1)$ .

- a. Let  $(\beta, 1 - \beta) \in \Delta(\mathcal{R}(Y))$  be a distribution over the range of  $Y$ . Give the set of  $\beta$  for which  $\operatorname{argmax}_{a \in A} \int u(a, y) d\beta(y) = \{1\}$ ,  $\operatorname{argmax}_{a \in A} \int u(a, y) d\beta(y) = \{2\}$ , and  $\operatorname{argmax}_{a \in A} \int u(a, y) d\beta(y) = \{3\}$ .
  - b. Give the  $\beta_x^X$  and the  $\beta_{x'}^{X'}$ . Using the previous problem, give the solutions  $f_X^*$  and  $f_{X'}^*$  to the problems  $\max_{f \in A^S} E u(f(X), Y)$  and  $\max_{f \in A^S} E u(f(X'), Y)$ . From these calculate  $V_{(u,A)}(X)$  and  $V_{(u,A)}(X')$ . [You should find that  $X' \succ_{(u,A)} X$ .]
  - c. Let  $M = (\beta_x^X, P(X = x))_{x=1,2} \in \Delta(\Delta(\mathcal{R}(Y)))$  and  $M' = (\beta_{x'}^{X'}, P(X' = x'))_{x'=1,2} \in \Delta(\Delta(\mathcal{R}(Y)))$ . Show directly that  $M$  is not riskier than  $M'$  and that  $M'$  is not riskier than  $M$ .
  - d. Graph, in  $\mathbb{R}^2$ , the sets of achievable,  $Y$ -dependent utility vectors for the random variables  $X$  and  $X'$ . That is, graph
 
$$F_{(u,A)}(X) = \{(E(u(f(X), Y)|Y = 1), E(u(f(X), Y)|Y = 2)) \in \mathbb{R}^2 : f \in A^S\}$$
 and
 
$$F_{(u,A)}(X') = \{(E(u(f(X'), Y)|Y = 1), E(u(f(X'), Y)|Y = 2)) \in \mathbb{R}^2 : f \in A^S\}.$$
  - e. If we allow random strategies, that is, pick  $f$  according to some  $q \in \Delta(A^S)$ , then the sets of achievable  $Y$ -dependent utility vectors become  $\mathbf{con}(F_{(u,A)}(X))$  and  $\mathbf{con}(F_{(u,A)}(X'))$ . Show that the same is true if we allow “behavioral strategies,” that is,  $f \in \Delta(A)^S$ .
  - f. Show that  $\mathbf{con}(F_{(u,A)}(X)) \not\subset \mathbf{con}(F_{(u,A)}(X'))$  and  $\mathbf{con}(F_{(u,A)}(X')) \not\subset \mathbf{con}(F_{(u,A)}(X))$ .
  - g. Give a different problem,  $(u^\circ, A^\circ)$  for which  $X \succ_{(u^\circ, A^\circ)} X'$ .
2. Let  $X, X'$  be two signals, and define  $X'' = (X, X')$  to be both signals. Let  $S, S'$  and  $S''$  be the ranges of the three signals
- a. Show directly that for all  $(u, A)$ ,  $X'' \succ_{(u,A)} X$  (hence  $X'' \succ_{(u,A)} X'$ ).
  - b. Show directly that  $\{(\beta_{x''}^{X''}, P(X'' = x''))_{x'' \in S''}\}$  is riskier than  $\{(\beta_x^X, P(X = x))_{x \in S}\}$ .
  - c. Interpret  $X$  as the result of a doctor’s diagnostic test and  $X'$  is the result of a possible additional test. Show that if  $f_{(X,X')}^*(x, x') = f_X^*(x)$  for a problem  $(u, A)$ , then there is no point in doing the extra test.
3. Most of the following results are in the Müller [1] article, which covers and extends the famous Rothschild and Stiglitz [2], [3] articles on increases in risk.
- a. If  $q$  is a mean preserving spread of  $p$ , then  $q$  is riskier than  $p$ .
  - b. If  $X \sim p$  (i.e.  $P(X \in A) = p(A)$ ),  $Y \sim q$ , and there is a random variable  $Z$  such that  $E(Z|X) = 0$  and  $X + Z \sim q$ , then  $q$  is riskier than  $p$ .

- c. Let  $p_0 = \delta_0$ ,  $p_1 = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_1$ . Let  $p_2 = \frac{1}{2}\delta_{-1} + \frac{1}{4}\delta_0 + \frac{1}{4}\delta_2$ , and  $p_3 = \frac{1}{4}\delta_{-2} + \frac{1}{4}\delta_0 + \frac{1}{4}\delta_0 + \frac{1}{4}\delta_2 = \frac{1}{4}\delta_{-2} + \frac{1}{2}\delta_0 + \frac{1}{4}\delta_2$ . Continuing in this fashion,  $p_4 = \frac{1}{8}\delta_{-4} + \frac{6}{8}\delta_0 + \frac{1}{8}\delta_4$ , and so on.
- i. Show that  $p_1$  is a mean preserving spread of  $p_0$ .
  - ii. Show that  $p_{k+1}$  is a mean preserving spread of  $p_k$ .
  - iii. Show that  $p_k \rightarrow_w p_0$ .
- d. The previous problem showed that a sequence can become riskier and riskier and still converge to something that is strictly less risky. Show that this cannot happen if  $p_k([a, b]) \equiv 1$  for some compact interval  $[a, b]$ . Specifically, show that if  $p_k([a, b]) \equiv 1$ , for all  $k$ ,  $p_{k+1}$  is riskier than  $p_k$ , and  $p_k \rightarrow q$ , then  $q$  is riskier than all of the  $p_k$ .
4. In each time period,  $t = 1, \dots$ , a random wage offer,  $X_t \geq 0$ , arrives. The  $X_t$  are iid with cdf  $F$ . The problem is which offer to accept. If offer  $X_t = x$  is accepted, utility is  $\beta^t u(x)$  where  $0 < \beta < 1$ , and  $u : \mathbb{R}_+ \rightarrow \mathbb{R}$  is strictly monotonic, concave, and  $\int u(x) dF(x) < \infty$ . A “reservation wage” policy is one that accepts all offers of  $\underline{x}$  or above for some  $\underline{x}$ .
- a. Show that the optimal policy is a reservation wage policy, and give the distribution of the random time until an offer is expected.
  - b. In terms of  $u$  and  $F$ , give the expected utility of following a reservation wage policy with reservation wage  $\underline{x}$ .
  - c. If the offers are, instead, iid  $Y_t$  with cdf  $G$  and  $G$  is riskier than  $F$ , then the optimal reservation wage is higher, and the expected utility is also higher.
5.  $X_a$  is your random income depending on your action  $a \geq 0$ , understood as money that you spend on stochastically increasing  $X_a$ . The distribution of  $X_a$  is  $R_{a,c} := cQ_a + (1 - c)\mu$ ,  $0 \leq c \leq 1$ . Here,  $\mu$  does not depend on  $a$ , but, if  $a > a'$ , then  $Q_a$  first order stochastically dominates  $Q_{a'}$ . The parameter  $c$  is the amount of “control” that you have,  $c = 0$  means you have no control,  $c = 1$ , means you have the most possible. This question asks you how  $a^*$  depends on  $c$ . Intuitively, increasing  $c$  ought to increase the optimal action, more control means that your actions have more effect.

Let  $f(a, c) = Eu(X_a - a)$  where  $u$  is an increasing, concave function. Increases in  $a$  pull down  $X_a - a$ , hence  $u(X_a - a)$ , by increasing the direct cost, but increase  $X_a - a$  by stochastically increasing  $X_a$ .

- a. Show that  $f(\cdot, \cdot)$  is not, in general, supermodular.
- b. Suppose that  $f(a, c)$  is smooth, that we can interchange integration and differentiation, and that the optimum,  $a^*(c)$  is differentiable. The  $f_a := \partial f / \partial a$  is equal to

$$f_a = - \int u'(x - a) d\mu(x) + cd/da[\text{messy term with } Q_a \text{ and } \mu].$$

We let  $m = [\text{messy term with } Q_a \text{ and } \mu]$ .

- i. Show that if  $f_a(a, c) = 0$ , then  $\partial m(a, c) / \partial a > 0$ .
- ii. Show that  $f_{a,c} := \partial^2 f / \partial a \partial c = \partial m / \partial a > 0$ .
- iii. Show that  $da^*(c) / dc > 0$ .

## REFERENCES

1. Alfred Müller, *Comparing risks with unbounded distributions*, J. Math. Econom. **30** (1998), no. 2, 229–239. MR MR1652641 (99m:90049)
2. Michael Rothschild and Joseph E. Stiglitz, *Increasing risk. I. a definition*, J. Econom. Theory **2** (1970), 225–243. MR MR0503565 (58 #20284a)
3. ———, *Increasing risk. II. Its economic consequences*, J. Econom. Theory **3** (1971), 66–84. MR MR0503567 (58 #20284c)